## Testhouse

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Final

## Test Report

| Device Under Test |  |
| :--- | :--- |
| Device Name | CA-IF1042 |
| Manufacturer | Chipanalog |
| Type | CA-IF1042VS-Q1 |
| Sample marking | 1042QS-V1 41930 120 <br> GUE02149E |

## P22_0116-1_005_IOPT_IF1042VS_report00 Date of Approval: 2022-Mar-10

Customer
Order No. P20_0191
Name Shanghai Chipanalog Microelectronics Co.,LTD

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## Number of Pages

Test Period

Test Method / Test Requirement

Performed Tests and References

## Conformance Test Results

1 Homogeneous Network with 16 Nodes / 8 Nodes

Heterogeneous Network with
16 Nodes - Mix of 6 8 Nodes - Mix of 5

2 Test type 1, static test cases

20
from ww06/2022 until ww07/2022

## CAN IOPT Test for devices <br> - with CAN FD up to $5 \mathrm{Mbit} / \mathrm{s}$ - with low power

1 Interoperability test specification for high-speed CAN transceiver or equivalent devices IOPT.CAN v02d06
2 Static Tests based on:
ISO 16845-2:2018, Road vehicles - Controller area network (CAN) conformance test plan - Part 2: Highspeed medium access unit - Conformance test plan

The Test Results refer to the delivered device.
Pass

## Pass

Pass

For detailed information see chapter Test List at the following pages.
This Test Report shall not be reproduced without written approval of the test house, except in full and unchanged.

Approved by Test performed by

[^0]K. Tadajan, Project Engineer

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## Revision History

| Old <br> revision | New <br> revision | Amendment Description | Editor |
| :--- | :--- | :--- | :--- |
| - | 00 | Final version | KT |

## 1 Device Under Test (detailed)

| General |  |
| :--- | :--- |
| Date of Sample Arrival | 09.02 .2022 |
| Manufacturer | Chipanalog |
| Sample Marking | $1042 \mathrm{QS}-\mathrm{V} 141930120$ GUE02149E |
| Test performed with DUT no. | \#01 to \#16 // \#01 to \#08 (homogenous) <br> \#01 to \#04 // \#01 to \#02 (mixed) |


| Device Specification | CA-IF1042 |
| :--- | :--- |
| Name | CA-IF1042VS-Q1 |
| Version | - |
| Design step |  |


| Documentation |  |
| :--- | :--- |
| User manual / datasheet | CA-IF1042_datasheet_version1.01_en_20220301 |

Device Classification
CAN FD Transceiver
Data rates up to $5 \mathrm{Mbit} / \mathrm{s}$

## 2 Setup for Device Under Test

Standard CAN HS Transceiver with 8 pins.
Vio connected to Vcc (5V)


Figure 6-1 CA-IF1042x Pin Configuration

## 3 Test Equipment

The following test equipment and test system have been used.

| No. | Component | Manufacturer | Version / Type | Network |
| :--- | :--- | :--- | :--- | :--- |
| 1 | IOPT.CAN Tester T1 | C\&S | v1.1.0.232 | mixed |
| 2 | IOPT.CAN Tester T2 | C\&S | v1.1.0.232 | homog |
| 3 | UT software version | C\&S | CA-IF1042 |  |

## 4 Technical Correspondence

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## 5 Test List

### 5.1 Static Conformance Tests (ISO 16845-2:2018)

## Used data sheet:

CA-IF1042_datasheet_version1.01_en_20220301
"The motivation of static test cases is to check the availability and the boundaries in the data sheet of the IUT. For all integrated circuits every related parameter in Table 4 shall be part of the data sheet and fulfil the specified boundaries in terms of physical worst-case condition. Data sheet parameter names may deviate from the names in Table 4, but in this case a cross-reference list (data sheet versus Table 4) shall be provided for this test. Parameter conditions may deviate from the conditions in Table 4, if the data sheet conditions are according to the physical worst-case context in Table 4."

## HS-PMA types:

a - without low-power mode and partial network,
b - with low-power mode, normal biasing and without partial network,
c - with low-power mode, automatic biasing and without partial network, n/a
d - with low-power mode, automatic biasing and partial network; n/a

| No. | Parameter | $\begin{gathered} \text { Reference } \\ \text { to ISO } \\ \text { 11898- } \\ 2: 2016 \end{gathered}$ | Limits |  |  | ${ }^{d}$ Parameters within the conditions are aligned with Figure 4 p for test. | Conformance test is passed if value |  | Rating |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Max | Unit |  | $\leq$ | $\geq$ |  |
| 1 | General maximum rating $V_{\text {CAN_H }}$ and $V_{\text {Can L }}$ | Table 15 | -27,0 | +40,0 | V | -/- | min | Max | Pass <br> 7.1 <br> $V_{\text {BUS }}$ |
| 2 | Extended maximum rating $\mathrm{V}_{\text {CAN_H }}$ and $V_{\text {CAN_L }}$ (if supported) | Table 15 | -58,0 | +58,0 | V | -/- | min | Max | Pass <br> 7.1 <br> $V_{\text {BUS }}$ |
| 3 | Maximum rating $\mathrm{V}_{\text {Diff }}$ | Table 15 | -5,0 | +10,0 | V | The maximum rating for $\mathrm{V}_{\text {Diff }}$ excludes that all combinations of $\mathrm{V}_{\text {CAN_H }}$ and $V_{\text {CAN_L }}$ are compliant to this standard. <br> $V_{\text {Diff }}=\mathrm{V}_{\text {CAN_H }}-\mathrm{V}_{\text {CAN_L. }}$ This is required regardless whether general or extended maximum rating for $\mathrm{V}_{\text {CAN_H }}$ and $V_{\text {Can_L }}$ is fulfilled | min | Max | Pass <br> 7.1 <br> $\mathrm{V}_{\text {(DIFF) }}$ |
| 4 | Single ended recessive output voltage on CAN_H ( $\mathrm{V}_{\text {CAN_H }}$ ), bus biasing active | Table 5 | +2,0 | +3,0 | V | All requirements in Table 5 apply concurrently. Therefore, not all combinations of $\mathrm{V}_{\text {CAN_H }}$ and $\mathrm{V}_{\text {CAN_L }}$ are compliant with the defined differential output voltage. See also ISO 11898-2:2016, Table 5. | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\mathrm{O} \text { (REC) }}$ |
| 5 | Single ended recessive output voltage on CAN_L ( $\mathrm{V}_{\text {CAN L }}$ ), bus biasing active | Table 5 | +2,0 | +3,0 | V | All requirements in Table 5 apply concurrently. Therefore, not all combinations of $\mathrm{V}_{\text {CAN_H }}$ and $\mathrm{V}_{\text {CAN_L }}$ are compliant with the defined differential output voltage. See also ISO 11898-2:2016, Table 5. | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\mathrm{O} \text { (REC) }}$ |
| 6 | Differential recessive output voltage $\left(\mathrm{V}_{\text {Diff }}\right)$, bus biasing active | Table 5 | -0,5 | +0,05 | V | All requirements in Table 5 apply concurrently. Therefore, not all combinations of $\mathrm{V}_{\text {CAN_H }}$ and $\mathrm{V}_{\text {CAN_L }}$ are compliant with the defined differential output voltage. See also ISO 11898-2:2016, Table 5. | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\mathrm{OD} \text { (REC) }}$ |


| No. | Parameter | $\begin{aligned} & \text { Reference } \\ & \text { to ISO } \\ & \text { 11898- } \\ & \text { 2:2016 } \end{aligned}$ | Limits |  |  | ${ }^{d}$ Parameters within the conditions are aligned with Figure 4 p for test. | Conformance test is passed if value |  | Rating |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Max | Unit |  | $\leq$ | $\geq$ |  |
| 7 | Single ended recessive output voltage on CAN_H ( $\left.\mathrm{V}_{\text {CAN_h }}\right)$, bus biasing inactive | Table 6 | -0,1 | +0,1 | V | See ISO 11898-2:2016, 5.10 to determine when bias shall be inactive. See also ISO 11898-2:2016, Table 6. | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\mathrm{O} \text { (STB) }}$ |
| 8 | Single ended recessive output voltage on CAN_L (VCAN_L), bus biasing inactive | Table 6 | -0,1 | +0,1 | V | See ISO 11898-2:2016, 5.10 and Table 6. | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\mathrm{O}(\mathrm{STB})}$ |
| 9 | Differential recessive output voltage ( $\mathrm{V}_{\text {Diff }}$, bus biasing inactive | Table 6 | -0,2 | +0,2 | V | See ISO 11898-2:2016, 5.10 and Table 6. | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\mathrm{O} \text { (STB) }}$ |
| 10 | Single ended voltage on CAN_H, dominant output (VCAN_H) | Table 2 | +2,75 | +4,50 | V | $\mathrm{R}_{\mathrm{L}}=50 \Omega \ldots 65 \Omega$ | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\mathrm{O}(\mathrm{DOM})}$ |
| 11 | Single ended voltage on CAN_L, dominant output (VCANL) | Table 2 | +0,5 | +2,25 | V | $\mathrm{R}_{\mathrm{L}}=50 \Omega \ldots 65 \Omega$ | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\mathrm{O} \text { (DOM) }}$ |
| 12 | Differential voltage on normal bus load, dominant output ( $\mathrm{V}_{\text {Difit }}$ ) | Table 2 | +1,5 | +3,0 | V | $\mathrm{R}_{\mathrm{L}}=50 \Omega \ldots 65 \Omega$ | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\mathrm{OD}(\mathrm{DOM})}$ |
| 13 | Differential voltage on effective resistance during arbitration, dominant output ( $\left.\mathrm{V}_{\text {Difit }}\right)$ | Table 2 | +1,5 | +5,0 | V | $\mathrm{R}_{\mathrm{L}}=2240 \Omega$ | max | min | Pass <br> 7.5 <br> $\mathrm{V}_{\text {OD(DOM) }}$ |
| 14 | Differential voltage on extended bus load, dominant output ( $\mathrm{V}_{\text {Diff }}$ ) (if supported) | Table 2 | +1,4 | +3,3 | V | $\mathrm{R}_{\mathrm{L}}=45 \Omega \ldots 70 \Omega$ | max | min | Not supported |
| 15 | Driver symmetry ( $\mathrm{V}_{\mathrm{SYM}}$ ), with a frequency that corresponds to the highest bit rate for which the HS-PMA implementation is intended, however, at most 1 MHz (2 MBit/s) | Table 3 | +0,9 | +1,1 | -/- | $\mathrm{R}_{\mathrm{L}}=60 \Omega ; \mathrm{C}_{1}=4,7 \mathrm{nF}$ | max | min | $\begin{aligned} & \text { Pass } \\ & 7.5 \\ & \mathrm{~V}_{\mathrm{SYM}} \end{aligned}$ |
| 16 | Absolute current on CAN_H (ICAN_H), Maximum driver output current | Table 4 | -/- | +115 | mA | $\begin{aligned} & -3,0 \mathrm{~V} \leq \mathrm{V}_{\text {CAN_H }} \leq+18,0 \mathrm{~V} \\ & \text { See also } \\ & \text { ISO 11898-2:2016, Table } 4 . \end{aligned}$ | max | --- | Pass <br> 7.5 <br> los(ss_Dом) |


| No. | Parameter | $\begin{gathered} \text { Reference } \\ \text { to ISO } \\ \text { 11898- } \\ \text { 2:2016 } \end{gathered}$ | Limits |  |  | ${ }^{\text {a }}$ Parameters within the conditions are aligned with Figure 4 p for test. | Conformance test is passed if value |  | Rating |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Max | Unit |  | $\leq$ | $\geq$ |  |
| 17 | Absolute current on CAN_L (ICAN_L), Maximum driver output current | Table 4 | --- | +115 | mA | $\begin{aligned} & -3,0 \mathrm{~V} \leq \mathrm{V}_{\text {CAN } \_L} \leq+18,0 \mathrm{~V} \\ & \text { See also } \\ & \text { ISO 11898-2:2016, Table } 4 . \end{aligned}$ | max | --- | Pass <br> 7.5 <br> los(Ss_DOM) |
| 18 | Transmit dominant time out ( $\mathrm{t}_{\text {dom }}$ ), <br> (if supported) <br> b) The minimum value of $0,3 \mathrm{~ms}$ is accepted for legacy implementations. | Table 7 | $+0,8^{\text {b }}$ | +10,0 | ms | -/- | max | min | Pass <br> 7.6 <br> $\mathrm{t}_{\mathrm{DOM}}$ |
| 19 | Receiver recessive state differential input voltage range, bus biasing active ( $\mathrm{V}_{\text {Diff }}$ ) | Table 8 | -3,0 | +0,5 | V | $\begin{aligned} & -12,0 \vee \leq V_{\text {CAN } L} \leq+12,0 \mathrm{~V} \\ & -12,0 \vee \leq \mathrm{V}_{\text {CAN_H }} \leq+12,0 \mathrm{~V} \end{aligned}$ | min | max | $\begin{aligned} & \text { Pass } \\ & 7.5 \\ & \text { V }_{\text {DIFF_R }} \end{aligned}$ |
| 20 | Receiver dominant state differential input voltage range, bus biasing active ( $\mathrm{V}_{\text {Diff }}$ ) | Table 8 | +0,9 | +8,0 | V | $\begin{aligned} & -12,0 \vee \leq V_{\text {CAN } L} \leq+12,0 \mathrm{~V} \\ & -12,0 \mathrm{~V} \leq \mathrm{V}_{\text {CAN_H }} \leq+12,0 \mathrm{~V} \end{aligned}$ | min | max | Pass <br> 7.5 <br> VDTFF_D |
| 21 | Receiver recessive state differential input voltage range, bus biasing inactive ( $\mathrm{V}_{\text {Diff }}$ ), (if supported) | Table 9 | -3,0 | +0,4 | V | $\begin{aligned} & -12,0 \vee \leq V_{\text {CAN } L} \leq+12,0 \mathrm{~V} \\ & -12,0 \mathrm{~V} \leq \mathrm{V}_{\text {CAN }-\mathrm{H}} \leq+12,0 \mathrm{~V} \end{aligned}$ | min | max | $\begin{aligned} & \text { Pass } \\ & 7.5 \\ & \text { V }_{\text {DIFF_R(STB) }} \end{aligned}$ |
| 22 | Receiver dominant state differential input voltage range, bus biasing inactive $\left(V_{\text {Diff }}\right)$, (if supported) | Table 9 | +1,15 | +8,0 | V | $\begin{aligned} & -12,0 \vee \leq V_{\text {CAN } L} \leq+12,0 \mathrm{~V} \\ & -12,0 \vee \leq \mathrm{V}_{\text {CAN_H }} \leq+12,0 \mathrm{~V} \end{aligned}$ | min | max | Pass <br> 7.5 <br> $V_{\text {DTFF_D(STB) }}$ |
| 23 | Differential internal resistance, receiver input resistance ( $\mathrm{R}_{\text {Diff }}$ ) | Table 10 | 12 | 100 | $k \Omega$ | $\begin{aligned} & -2,0 \vee \leq \mathrm{V}_{\mathrm{CAN} \_\mathrm{H}} \leq+7,0 \mathrm{~V} \\ & -2,0 \leq \leq \mathrm{V}_{\text {CAN } L} \leq+7,0 \mathrm{~V} \end{aligned}$ | max | min | Pass <br> 7.5 <br> $\mathrm{R}_{\text {DIFF }}$ |
| 24 | Single ended internal resistance, receiver input resistance ( $\mathrm{R}_{\text {CAN_H }}, \mathrm{R}_{\text {CAN_L }}$ ) | Table 10 | 6 | 50 | $k \Omega$ | $\begin{aligned} & -2,0 \vee \leq \mathrm{V}_{\text {CAN } H} \leq+7,0 \mathrm{~V} \\ & -2,0 \mathrm{~V} \leq \mathrm{V}_{\text {CANL }} \leq+7,0 \mathrm{~V} \end{aligned}$ | max | min | $\begin{aligned} & \text { Pass } \\ & 7.5 \\ & \mathrm{R}_{\mathrm{IN}} \end{aligned}$ |
| 25 | Matching of receiver internal resistance ( $\mathrm{m}_{\mathrm{R}}$ ) | Table 11 | -0,03 | +0,03 | -/- | $\begin{aligned} & V_{\text {CAN } H}=+5,0 \mathrm{~V} \\ & \mathrm{~V}_{\text {CAN L }}=+5,0 \mathrm{~V} \end{aligned}$ | max | min | Pass <br> 7.5 <br> $\mathrm{R}_{\text {DIFF(M) }}$ |
| 26 | Loop delay ( t Loop $^{\text {) }}$ | Table 12 | -/- | 255 | ns | $\mathrm{R}_{\mathrm{L}}=60 \Omega, \mathrm{C}_{2}=100 \mathrm{pF}, \mathrm{C}_{\mathrm{RXD}}=15 \mathrm{pF}$ | max | -/- | Pass <br> 7.6 <br> $t_{\text {loop }}, t_{\text {loop2 }}$ |


| No. | Parameter | $\begin{aligned} & \text { Reference } \\ & \text { to ISO } \\ & \text { 11898- } \\ & 2: 2016 \end{aligned}$ | Limits |  |  | ${ }^{d}$ Parameters within the conditions are aligned with Figure 4 p for test. | Conformance test is passed if value |  | Rating |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Max | Unit |  | $\leq$ | $\geq$ |  |
| 27 | Transmitted recessive bit width @ $2 \mathrm{Mbit} / \mathrm{s}$ (t.tit(Bus)), (if supported) | Table 13 | 435 | 530 | ns | $\mathrm{R}_{\mathrm{L}}=60 \Omega, \mathrm{C}_{2}=100 \mathrm{pF}, \mathrm{C}_{\mathrm{RXD}}=15 \mathrm{pF}$ | max | min | Pass <br> 7.6 <br> tbit(bus) |
| 28 | Received recessive bit width @ 2 Mbit/s ( $\mathrm{t}_{\text {Bit (RXD) }}$ ), (if supported) | Table 13 | 400 | 550 | ns | $\mathrm{R}_{\mathrm{L}}=60 \Omega, \mathrm{C}_{2}=100 \mathrm{pF}, \mathrm{C}_{\mathrm{RXD}}=15 \mathrm{pF}$ | max | min | Pass <br> 7.6 <br> $t_{\text {bit }}$ (rxd) |
| 29 | Receiver timing symmetry @ 2 Mbit/s ( $\Delta \mathrm{t}_{\text {Rec }}$ ), (if supported) | Table 13 | -65 | +40 | ns | $\mathrm{R}_{\mathrm{L}}=60 \Omega, \mathrm{C}_{2}=100 \mathrm{pF}, \mathrm{C}_{\mathrm{RXD}}=15 \mathrm{pF}$ | max | min | Pass <br> 7.6 <br> trec |
| 30 | Transmitted recessive bit width @ $5 \mathrm{Mbit} / \mathrm{s}$ (t.tit(Bus) $)$, (if supported) | Table 14 | 155 | 210 | ns | $\mathrm{R}_{\mathrm{L}}=60 \Omega, \mathrm{C}_{2}=100 \mathrm{pF}, \mathrm{C}_{\text {RXD }}=15 \mathrm{pF}$ | max | min | Pass <br> 7.6 <br> $t_{\text {bit(bus) }}$ |
| 31 | Received recessive bit width @ 5 Mbit/s ( tiit(RXD) ), (if supported) | Table 14 | 120 | 220 | ns | $\mathrm{R}_{\mathrm{L}}=60 \Omega, \mathrm{C}_{2}=100 \mathrm{pF}, \mathrm{C}_{\mathrm{RXD}}=15 \mathrm{pF}$ | max | min | Pass <br> 7.6 <br> $t_{\text {bit(rxd) }}$ |
| 32 | Receiver timing symmetry @ 5 Mbit/s ( $\Delta \mathrm{t}_{\text {Rec }}$ ), (if supported) | Table 14 | -45 | +15 | ns | $\mathrm{R}_{\mathrm{L}}=60 \Omega, \mathrm{C}_{2}=100 \mathrm{pF}, \mathrm{C}_{\text {RXD }}=15 \mathrm{pF}$ | max | min | Pass <br> 7.6 <br> $\mathrm{t}_{\text {rec }}$ |
| 33 | Leakage current on CAN_H, CAN_L (ICAN_H, $I_{\text {CAN_L }}$ ), maximum leakage currents, unpowered | Table 16 | -10 | +10 | $\mu \mathrm{A}$ | $\mathrm{V}_{\text {CAN_H }}=5 \mathrm{~V}, \mathrm{~V}_{\text {CAN } L}=5 \mathrm{~V},$ <br> All supply inputs connected to GND. | max | min | $\begin{aligned} & \text { Pass } \\ & 7.5 \\ & \text { LLKG }^{2} \end{aligned}$ |
| 34 | CAN activity filter time, long ( $\mathrm{t}_{\text {Filter }}$ ), (if supported) | Table 20 | 0,5 | 5,0 | $\mu \mathrm{s}$ | -/- | max | min | $\begin{aligned} & \text { Pass } \\ & 7.6 \\ & T_{\text {wk_FILTER }} \end{aligned}$ |
| 35 | CAN activity filter time, short ( $\mathrm{t}_{\text {Filter }}$ ), (if supported) | Table 20 | 0,15 | 1,8 | $\mu \mathrm{s}$ | -/- | max | min | $\begin{aligned} & \text { Pass } \\ & 7.6 \\ & T_{\text {wk_FILTER }} \end{aligned}$ |
| 36 | Wake-up timeout ( $\mathrm{t}_{\text {Wake }}$ ), <br> (if supported) <br> c) For legacy implementations a minimum value of $350 \mu$ s is acceptable. | Table 20 | 800, $0^{\text {c }}$ | 10000,0 | $\mu \mathrm{s}$ | -/- | max | min | $\begin{aligned} & \hline \text { Pass } \\ & 7.6 \\ & \text { TwK_FILTEROUT } \end{aligned}$ |
| 37 | Timeout for bus inactivity ( $\mathrm{t}_{\text {silece }}$ ) | Table 20 | $0,6 * 10^{6}$ | $1,2^{*} 10^{6}$ | $\mu \mathrm{s}$ | -/- | max | min | n/a |


| No. | Parameter | $\begin{gathered} \text { Reference } \\ \text { to ISO } \\ \text { 11898- } \\ 2: 2016 \end{gathered}$ | Limits |  |  | Conditions ${ }^{\text {d }}$ <br> ${ }^{\text {d }}$ Parameters within the conditions are aligned with Figure 4 p for test. | Conformance test is passed if value |  | Rating |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Min | Max | Unit |  | $\leq$ | $\geq$ |  |
| 38 | Bus Bias reaction time (tbais) | Table 20 | -/- | 250,0 | $\mu \mathrm{s}$ | -/- | max | -/- | n/a |
| 39 | Number of recessive bits before a new SOF shall be accepted ( $n_{\text {Bits }}$ dide $)$ (if supported) | Table 18 | 6 | 10 | -- | -- | max | min | n/a |
| 40 | CAN FD data phase glitch filter (slow) (pGlitch ${ }_{\text {sow }}$ ) <br> (if supported) | Table 19 | 5,00 | 17,50 | \% of arbitration bit time | --- | min | max | n/a |
| 41 | CAN FD data phase glitch filter (fast) ( $\mathrm{pGlitch}_{\text {Fast }}$ ) <br> (if supported) | Table 19 | 2,50 | 8,75 | \% of arbitration bit time | --- | min | max | n/a |

### 5.2 Dynamic Tests (CAN IOPT v02d06)

Following test case numeration relates on the corresponding test specification.
IOPT 5.4 -Tests in Homogeneous Network with 16 Nodes - 2 Mbit/s with wake-up via bus for " $5 \mathrm{Mbit} / \mathrm{s}$ Devices"

| No. | Tests in Homogeneous Network with 16 Nodes - 2 Mbit/s with wake-up via bus | Result | Comment |
| :---: | :---: | :---: | :---: |
| 5.4.1 | Test Flow 1 <br> Op. mode variation after recovery at normal mode, failure application on startup |  | Performed in 8-node-network with 5 Mbit/s |
| 5.4.1.1.x | GND Shift = 0V | n/a |  |
| 5.4.1.2.x | GND Shift $=+1 \mathrm{~V}$ | n/a |  |
| 5.4.1.3.x | GND Shift $=-1 \mathrm{~V}$ | n/a |  |
| 5.4.2 | Test Flow 2 <br> Op. mode variation after recovery at normal mode, failure application in normal mode |  | 4224 Test cases |
| 5.4.2.1.x | GND Shift = 0V | E/Pass |  |
| 5.4.2.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 5.4.2.3.x | GND Shift = -1V | E/Pass |  |
| 5.4.3 | Test Flow 3 <br> Op. mode variation before recovery at normal Mode, failure application in normal mode |  | 4224 test cases |
| 5.4.3.1.x | GND Shift = 0V | E/Pass |  |
| 5.4.3.2.x | GND Shift = +1V | E/Pass |  |
| 5.4.3.3.x | GND Shift = -1V | E/Pass |  |
| 5.4.4 | Test Flow 4 <br> Op. mode variation with failure before recovery at normal mode, failure application on startup |  | 264 Test cases |
| 5.4.4.1.x | GND Shift = 0V | E/Pass |  |
| 5.4.4.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 5.4.4.3.x | GND Shift $=-1 \mathrm{~V}$ | E/Pass |  |


| No. | Tests in Homogeneous Network with 16 Nodes - 2 Mbit/s with wake-up via bus | Result | Comment |
| :---: | :---: | :---: | :---: |
| 5.4.5 | Test Flow 5 <br> Op. mode variation with failure before recovery at low-power mode, failure application in normal mode |  | 4224 Test cases |
| 5.4.5.1.x | GND Shift = 0V | E/Pass |  |
| 5.4.5.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 5.4.5.3.x | GND Shift $=-1 \mathrm{~V}$ | E/Pass |  |
| 5.4.6 | Test Flow 6 <br> Op. mode variation with failure before recovery at low-power mode, failure application in lowpower mode |  | 4224 Test cases |
| 5.4.6.1.x | GND Shift = 0V | E/Pass |  |
| 5.4.6.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 5.4.6.3.x | GND Shift = -1V | E/Pass |  |
| 5.4.7 | Test Flow 7 <br> Op. mode variation with failure before recovery at normal mode, failure application in lowpower mode |  | 264 Test cases |
| 5.4.7.1.x | GND Shift = 0V | E/Pass |  |
| 5.4.7.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 5.4.7.3.x | GND Shift $=-1 \mathrm{~V}$ | E/Pass |  |

Signs and symbols

E executed

## IOPT 5.4 -Tests in Homogeneous Network with 8 Nodes - 5 Mbit/s with wake-up via bus

| No. | Tests in Homogeneous Network with 8 Nodes -5 Mbit/s with wake-up via bus | Result | Comment |
| :--- | :--- | :--- | :--- |
| 5.4 .1 | Test Flow 1 <br> Op. mode variation after recovery at normal mode, failure application on startup | 1088 Test cases |  |
| 5.4.1.1.x | GND Shift $=0 \mathrm{~V}$ | E/Pass |  |
| $5.4 .1 .2 . \mathrm{x}$ | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| $5.4 .1 .3 . \mathrm{x}$ | GND Shift $=-1 \mathrm{~V}$ | E/Pass |  |

Signs and symbols
E executed

IOPT 6.4-Tests in Heterogeneous Network with 16 Nodes - 2 Mbit/s with wake-up via bus for " 5 Mbit/s Devices"

| No. | Tests in Heterogeneous Network with 16 Nodes $\mathbf{- 2}$ Mbit/s with wake-up via bus - Mix of 6*: 2xA / 3xB / 2xC / 2xD / 3xE / 4xIUT | Result | Comment |
| :---: | :---: | :---: | :---: |
| 6.4.1 | Test Flow 1 <br> Op. mode variation after recovery at normal mode, failure application on startup |  | Performed in 8-node-network with 5 Mbit/s |
| 6.4.1.1.x | GND Shift = 0V | n/a |  |
| 6.4.1.2.x | GND Shift $=+1 \mathrm{~V}$ | n/a |  |
| 6.4.1.3.x | GND Shift $=-1 \mathrm{~V}$ | n/a |  |
| 6.4.2 | Test Flow 2 <br> Op. mode variation after recovery at normal mode, failure application in normal mode |  | 4224 Test cases |
| 6.4.2.1.x | GND Shift = 0V | E/Pass |  |
| 6.4.2.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 6.4.2.3.x | GND Shift $=-1 \mathrm{~V}$ | E/Pass |  |
| 6.4.3 | Test Flow 3 <br> Op. mode variation before recovery at normal Mode, failure application in normal mode |  | 4224 Test cases |
| 6.4.3.1.x | GND Shift = 0V | E/Pass |  |
| 6.4.3.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 6.4.3.3.x | GND Shift = -1V | E/Pass |  |
| 6.4.4 | Test Flow 4 <br> Op. mode variation with failure before recovery at normal mode, failure application on startup |  | 264 Test cases |
| 6.4.4.1.x | GND Shift = 0V | E/Pass |  |
| 6.4.4.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 6.4.4.3.x | GND Shift $=-1 \mathrm{~V}$ | E/Pass |  |


| No. | Tests in Heterogeneous Network with 16 Nodes $\mathbf{- 2}$ Mbit/s with wake-up via bus - Mix of 6*: 2xA / 3xB / 2xC / 2xD / 3xE / 4xIUT | Result | Comment |
| :---: | :---: | :---: | :---: |
| 6.4.5 | Test Flow 5 <br> Op. mode variation with failure before recovery at low-power mode, failure application in normal mode |  | 4224 Test cases |
| 6.4.5.1.x | GND Shift = 0V | E/Pass |  |
| 6.4.5.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 6.4.5.3.x | GND Shift = -1V | E/Pass |  |
| 6.4.6 | Test Flow 6 <br> Op. mode variation with failure before recovery at low-power mode, failure application in lowpower mode |  | 4224 Test cases |
| 6.4.6.1.x | GND Shift = 0V | E/Pass |  |
| 6.4.6.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 6.4.6.3.x | GND Shift = -1V | E/Pass |  |
| 6.4 .7 | Test Flow 7 <br> Op. mode variation with failure before recovery at normal mode, failure application in low-power mode |  | 264 Test cases |
| 6.4.7.1.x | GND Shift = 0V | E/Pass |  |
| 6.4.7.2.x | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| 6.4.7.3.x | GND Shift $=-1 \mathrm{~V}$ | E/Pass |  |

Signs and symbols
E executed

Abbreviations to identify components:

- $2 \times \mathrm{A}$ TJA1044GT
- $3 \times B$ TJA1043T
- $2 \times \mathrm{C}$ TLE9252
- $2 \times \mathrm{D}$ TLE9255WSK
- $3 \times \mathrm{E}$ TLE9251
- 4 x IUT Implementation Under Test

Positions of the reference devices in $500 \mathrm{kbit} / \mathrm{s}$ and $2 \mathrm{Mbit} / \mathrm{s}$ reference environments:

| Node: | $\# 1$ | $\# 2$ | $\# 3$ | $\# 4$ | $\# 5$ | $\# 6$ | $\# 7$ | $\# 8$ | $\# 9$ | $\# 10$ | $\# 11$ | $\# 12$ | $\# 13$ | $\# 14$ | $\# 15$ | $\# 16$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TRX: | B | A | IUT | C | E | D | IUT | B | E | A | IUT | B | C | D | IUT | E |

## IOPT 6.4 -Tests in Heterogeneous Network with 8 Nodes - 5 Mbit/s with wake-up via bus

| No. | Tests in Heterogeneous Network with 8 Nodes -5 Mbit/s with wake-up via bus <br> - Mix of $5^{\star}: 1 \times \mathrm{xA} / 2 \mathrm{xB} / 1 \mathrm{xC} / 2 \mathrm{xD} / 2 \mathrm{xIUT}$ | Result | Comment |
| :--- | :--- | :--- | :--- |
| 6.4 .1 | Test Flow 1 <br> Op. mode variation after recovery at normal mode, failure application on startup | 1088 Test cases |  |
| $6.4 .1 .1 . \mathrm{x}$ | GND Shift $=0 \mathrm{~V}$ | E/Pass |  |
| $6.4 .1 .2 . \mathrm{x}$ | GND Shift $=+1 \mathrm{~V}$ | E/Pass |  |
| $6.4 .1 .3 . \mathrm{x}$ | GND Shift $=-1 \mathrm{~V}$ | E/Pass |  |

Signs and symbols
E executed

Abbreviations to identify components:

- $1 \times \mathrm{A}$ TJA1044GT
- $2 \times B$ TJA1043T
- $1 \times C$ TLE9252
- $2 \times \mathrm{D}$ TLE9251
- 2 x IUT Implementation Under Test

Positions of the reference devices in $5 \mathrm{Mbit} / \mathrm{s}$ reference environments:

| Node: | \#1 | \#2 | \#3 | \#4 | \#5 | \#6 | \#7 | \#8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TRX: | A | B | IUT | C | B | D | IUT | D |


[^0]:    L. Kukla, Project Manager

